ANALYSIS OF ELECTROMAGNETIC FIELD USING THE CONSTRAINED INTERPOLATION PROFILE METHOD PHÂN TÍCH TRƯỜNG ĐIỆN TỪ SỬ DỤNG PHƯƠNG PHÁP CIP

LÊ VŨ HƯNG

Cao đẳng kỹ thuật quốc gia Kushiro, Nhật Bản Kushiro National College of Technology, Japan

ABSTRACT

A new time domain method, CIP (Constrained Interpolation Profile) method has been developed as a numerical solver for multi-phase problems. The method is based on the upwind scheme for the finite difference method, but the variables to be calculated are not only the values of the quantity, but also the spatial derivatives. This study uses CIP method to analyze one-dimensional electromagnetic field and compare with the FDTD (Finite Difference Time Domain) method.

TÓM TẮT

Một phương pháp miền thời gian mới. Phương pháp CIP (Constrained Interpolation Profile) được phát triển để tính toán số trị các vấn đề đa pha. Phương pháp CIP không chỉ tính toán giá trị chuyển động của trường mà còn tính cả vi phân không gian. Trong nghiên cứu này sử dụng phương pháp CIP để phân tích trường điện từ một chiều và tiến hành so sánh với phương pháp Sai phân miền thời gian (FDTD: Finite Difference Time Domain).

I. INTRODUCTION

Recently, time domain numerical analysis of electromagnetic (EM) fields has come to be investigated widely as a result of computer development. Development of accurate schemes is an important technical issue related to EM field calculation. Although many methods have been proposed, the finite-difference time-domain (FDTD) method is the most widely used method for time domain numerical analysis. However, the FDTD method solves Maxwell's equation using finite difference approximation. Using this approximation certainly causes error because of numerical dispersion. For that reason, EM field propagation cannot be analyzed exactly.

CIP method was proposed by Yabe.et.al. A noticeable feature of the CIP method is

advantageous that it allows analysis not only of EM fields on grid points, but also analysis of their spatial derivatives on grid points.

In this study, CIP method is applied to one-dimensional EM field equation (Maxwell's equation) and compare analytical results with the FDTD method.

II. CALCULATION

A. The Constrained interpolation profile method

Let us consider the linear wave propagation in non-uniform mesh system with an advection equation:



Fig. 1: The principle of the CIP method: (a) solid line is initial profile and dashed line is an exact solution after advection. (b) Spatial derivative also propagates and the profile inside a grid cell is retrieved.

$$\frac{\partial f}{\partial t} + v \frac{\partial f}{\partial x} = 0 \tag{1}$$

Then, let us differentiate Eq. (1) with spatial variable x, we get:

$$\frac{\partial g}{\partial t} + v \frac{\partial g}{\partial x} = -\frac{\partial v}{\partial x} g \tag{2}$$

Where g stands for the spatial derivative of $f(g = \frac{\partial f}{\partial x})$. In the simplest case where the velocity v is constant, Eq. (2) coincides with Eq. (1) and represents the propagation of spatial derivative with a velocity v.

If two values of f and g are given at two grid points, the profile between these points can be interpolated by cubic polynomial:

and

$$F_i(x) = a_i (x - x_i)^3 + b_i (x - x_i)^2 + c_i (x - x_i) + d_i$$
(3)

Here
$$F_{i}(x_{i}) = d_{i} = f_{i}$$
 (4)
 $\frac{dF_{i}(x_{i})}{dx} = c_{i} = g_{i}$ (5)
 $F_{i}(x_{i-1}) = -a_{i}\Delta x^{3} + b_{i}\Delta x^{2} - c_{i}\Delta x + d_{i} = f_{i-1}$ (6)
 $\frac{dF_{i}(x_{i-1})}{dx} = 3a_{i}\Delta x^{2} - 2b_{i}\Delta x + c_{i} = g_{i-1}$ (7)
and $\Delta x = x_{i} - x_{i-1}, D = -\Delta x$

From the conditions in the lefthand side the coefficients a_i and b_i can be described such as:

$$a_{i} = \frac{g_{i} + g_{i-1}}{D^{2}} + \frac{2(f_{i} - f_{i-1})}{D^{3}}$$
(8)

$$b_{i} = \frac{3(f_{i-1} - f_{i})}{D^{2}} - \frac{2g_{i} + g_{i-1}}{D}$$
(9)

Thus, the profile at the n+1 step can be obtained by shifting the profile by $v\Delta t$ so that:

$$f_i^{n+1} = a_i \xi^3 + b_i \xi^2 + g_i^n \xi + f_i^n$$

$$g_i^{n+1} = 3a_i \xi^2 + 2b_i \xi + g_i^n$$
(10)

$$f^{n+1} = F(x - v\Delta t), g^{n+1} = dF(x - v\Delta t)/dx$$

Where $\xi = -v\Delta t$.

B. Electromagnetic Field Numerical Analysis Using the CIP Method



Fig. 2: Propagation of EM. Propagation of $B_z \mp E_y$ with velocity v is constant.

$$\frac{\partial B_z}{\partial t} = c \frac{\partial E_y}{\partial x}$$
(13);

Faraday's and Ampere's laws are shown respectively as (11) and (12):

$$\frac{\partial B}{\partial t} = -c\nabla \times E \tag{11}$$

$$\nabla \times B = J + \frac{1}{c} \frac{\partial E}{\partial t}$$
(12)

Here, using CGS-Gauss system of unit and assuming $E = (0, E_y, 0), B = (0, 0, B_z)$ and J=0 in order to analyze one-dimensional EM field propagation of the x-direction in the vacuum, we can obtain the following equations from Eq. (11) and (12).

By addition and subtraction of Eq. (11) and (12), we obtion:

$$\frac{\partial E_{y}}{\partial t} = c \frac{\partial B_{z}}{\partial x}$$
(14)

In addition and subtraction of Eq. (13) and Eq. (14) for the derivative are also given as:

$$\frac{\partial (B_z + E_y)}{\partial t} - c \frac{\partial (B_z + E_y)}{\partial x} = 0 \quad (15); \qquad \qquad \frac{\partial (B_z - E_y)}{\partial t} + c \frac{\partial (B_z - E_y)}{\partial x} = 0 \quad (16)$$

It is readily apparent that equations from (13) to (16) are advection equations of $B_z \pm E_y$ and $\partial_x B_z \pm \partial_x E_y$. Therefore, application of the CIP method to these equations allows a solution of EM field propagation in the *x*-direction at time step *n*.

Next, we calculate the fields of the n+1 time step from the fields of n time step. Here, the calculation method of the $\pm x$ -direction propagation is described below using Fig. 2. Eq. (16) shows propagation of $B_z - E_y$ to i point with the velocity +c is constant. In Fig.2 shows propagation of $B_z^+ - E_y^+$ from A point to i point is become $B_z^{n+1} - E_y^{n+1}$. Eq. (15) shows propagation of $B_z^- + E_y^-$ to i point with the velocity -c is constant. Fig.2 shows propagation of $B_z^- + E_y^-$ from B point to i point is become $B_z^{n+1} - E_y^{n+1}$. Eq. (15) shows propagation of $B_z^- + E_y^-$ from B point to i point is become $B_z^{n+1} + E_y^{n+1}$. We can obtion:

$$B_{z}^{n+1} - E_{y}^{n+1} = B_{z}^{+} - E_{y}^{+}$$
(17);
$$B_{z}^{n+1} + E_{y}^{n+1} = B_{z}^{-} + E_{y}^{-}$$
(18)

In the *x*-direction, equations for the derivative are given as:

$$\frac{\partial B_z^{n+1}}{\partial x} - \frac{\partial E_y^{n+1}}{\partial x} = \frac{\partial B_z^+}{\partial x} - \frac{\partial E_y^+}{\partial x} \quad (19); \qquad \frac{\partial B_z^{n+1}}{\partial x} + \frac{\partial E_y^{n+1}}{\partial x} = \frac{\partial B_z^-}{\partial x} + \frac{\partial E_y^-}{\partial x} \quad (20)$$

Then, by addition and subtraction of these equations, we obtain:

$$B_{z}^{n+1} = \frac{(B_{z}^{-} + E_{y}^{-}) + (B_{z}^{+} - E_{y}^{+})}{2}$$
(21); $\partial_{x}B_{z}^{n+1} = \frac{(\partial_{x}B_{z}^{-} + \partial_{x}E_{y}^{-}) + (\partial_{x}B_{z}^{+} - \partial_{x}E_{y}^{+})}{2}$ (22)

$$E_{y}^{n+1} = \frac{(B_{z}^{-} + E_{y}^{-}) - (B_{z}^{+} - E_{y}^{+})}{2}$$
(23); $\partial_{x}E_{y}^{n+1} = \frac{(\partial_{x}B_{z}^{-} + \partial_{x}E_{y}^{-}) - (\partial_{x}B_{z}^{+} - \partial_{x}E_{y}^{+})}{2}$ (24)

Using the equations from (21) to (24), one can obtain EM field components of time step n+1.

From the above equations, $\partial_x = \frac{1}{\partial x}$

III. RESULTS AND DISCUSSION

We show the result of calculations in Section II. We calculate the EM field propagation in the one-dimensional analysis domain in the vacuum. In the original addition:

$$E_{y}(x) = \begin{cases} 1 & if \quad 0.4 \le x \le 0.6 \\ 0 & otherwise \end{cases} \quad \text{and} \quad B_{z}(x) = 0$$

Grid size, dx = 0.005m; time step, dt = 0.001s; number of grid points, *NX*=200. Fig. 3 and Fig. 4 shows the electric field waveform that is calculated using CIP method and Fig.5 and Fig. 6 shows the magnetic field waveform that is calculated using FDTD method at t = 0.0s, t = 0.05s and t = 0.25s.

All parameters of FDTD calculation are equal to those of the CIP calculation. Fig. 3, Fig. 4, Fig. 5 and Fig. 6 demonstrates that the CIP results provides accuracy. On the other hand, numerical oscillation appears in the FDTD result.

Next, we calculate the EM field propagation with the original addition using Gauss's distribution:





Fig. 3: Calculated results of Ey at t = 0.05s.



Fig. 4: Calculated results of Ey at t = 0.25s



Fig. 5: Calculated results of Bz at t = 0.05s. Fig. 6: Calculated results of Bz at t = 0.25s

$$E_{y}(x) = 1 + 0.5 \exp\left\{-\left(\frac{x-50}{\sigma}\right)^{2}\right\}, \quad B_{z}(x) = 0$$

Parameters of the calculation are as follows: Grid size, dx = 0.002m; time step, dt = 0.01s; number of grid points, *NX*=200.

Fig. 7, Fig. 8 and Fig. 9 shows the electric field waveform that are calculated using CIP analysis and FDTD analysis under the condition of $\sigma = 5.0$, $\sigma = 1.5$ and $\sigma = 0.05$ at t = 0.6s. When $\sigma = 5.0$, the results calculated using FDTD are equal to those of the CIP calculation. However, $\sigma = 1.5$ and $\sigma = 0.05$ numerical oscillation appears in the FDTD result.

III. CONCLUSION

In this paper, we have analyzed EM field using the CIP method. We consider the values not only of the EM field, but also of their spatial derivatives. The results obtained in this study have clarified that EM field analysis using the CIP method provides higher accuracy than that obtainable using the FDTD method.

According to these results, we intend to investigate actual one-dimensional analysis including boundaries in the near future.





Fig. 7: Calculated results of Ey at $\sigma = 5.0$

Fig. 8: Calculated results of Ey at



Fig. 9: Calculated results of Ey at

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Địa chỉ liên lạc của tác giả:

Lê Vũ Hưng, Khoa Kỹ thuật Điện, Cao đẳng kỹ thuật quốc gia Kushiro, Nhật Bản. Department of Electrical Engineering, Kushiro National College of Technology, Japan. 084-0916 Japan, Kushiro City, Otanoshike-Nishi 2-32-1 Email: <u>levuhung@gmail.com</u>