

1. AI in Robotics

PUT:

- 1.1. Introduction to Robotics
- 1.2. Robot Operating System – software architecture and tools
- 1.3. Robot Operating System – robots programming
- 1.4. Foundations of kinematics – coordinate systems and transformations
- 1.5. Kinematics of robotic manipulator, Robot kinematics in practical examples
- 1.6. Sensors and perception of robots
- 1.7. Advanced robot simulation in ROS 2 with MoveIt

UEC: Fundamental Robotics and Applications (tentative)

- 1.8. Medical Robotics
- 1.9. Bio-inspired Legged Robots
- 1.10. Micro Electro Mechanical Systems (MEMS)
- 1.11. Human Robot Interface
- 1.12. Robotic Manipulation
- 1.13. Human-Robot Interaction
- 1.14. Environmentally Harmonized Robotics

2. Cybersecurity

UEC: (Prof. Yuntao WANG)

- 2.1. An Introduction to Post-Quantum Cryptography (PQC): Research Background and Standardization Trends
- 2.2. PQC Cryptographic Schemes (1): LWE-Based Cryptosystems and Ring-LWE-Based Key Exchange
- 2.3. PQC Cryptographic Schemes (2): CRYSTALS-Kyber and Its Mathematical Background
- 2.4. PQC Cryptographic Schemes (3): Lattice-based Signatures
- 2.5. PQC Cryptographic Analysis (1): Lattice Enumeration and Lattice Reduction Algorithms
- 2.6. PQC Cryptographic Analysis (2): An Overview of Lattice Sieving and G6K
- 2.7. PQC Cryptographic Analysis (3): Mathematical Structure of Lattice Sieving and Its Applications to 2.14 Lattice Reduction Algorithms

PUT: (Prof. Mariusz Głębowski)

- 2.8. Foundations of Cybersecurity: Concepts, Threats and Defense Models
- 2.9. Modern Malware and Ransomware: Techniques, Analysis and Mitigation
- 2.10. Identity and Access Management: Authentication, Authorization and Federation
- 2.11. Network Security: From Firewalls and VPNs to Zero-Trust Architectures
- 2.12. Security of IoT, Industrial Control Systems and Critical Infrastructure
- 2.13. Incident Detection and Response: SOC Operations and Digital Forensics
- 2.14. Security Economics, Cyber Risk Management and Security Governance for Organizations

3. Hyper-connected world: Network infrastructure in HCW

PUT: Architectures and Performance Evaluation for HCW/Foundations and Network Design for HCW (Prof. Maciej Sobieraj)

- 3.1. Architectures of telecommunication networks in the hyper-connected world
- 3.2. Next-generation optical networks for HCW
- 3.3. Packet, wavelength switching and SDN in HCW infrastructure
- 3.4. Analytical performance modeling of networks in the hyper-connected world
- 3.5. Simulation of telecommunication and optical networks for HCW
- 3.6. Integration of heterogeneous access technologies in HCW
- 3.7. Intelligent network management and automation in the hyper-connected world

UEC: Optimization for HCW (Prof. Nattapong Kitsuwon)

- 3.8. Introduction and Basic problems for communication networks, algorithm for shortest path routing
- 3.9. Algorithm for max flow and minimum-cost flow problems
- 3.10. Disjoint path routing (Edge-disjoint, Vertex-Disjoint)
- 3.11. Linear Programming basics and applications
- 3.12. Introduction to Linear Programming solving software, GLPK (GNU Linear Programming Kit)
- 3.13. Basic problems solved by Linear Programming
- 3.14. Optimization for wavelength assignment and routing, and traffic-demand model

4. Hyper-connected world: Monitoring/automation/management in HCW

PUT: (Prof. Aleksandra Wojewoda)

- 4.1. DevOps Fundamentals and First Steps with Git
- 4.2. Repository Management ~~~and Cloud Platforms~~~ (GitHub/GitLab)
- 4.3. Collaborative Workflow: Pull Requests, Labels, and Releases
- 4.4. Introduction to Containerization: Docker Basics
- 4.5. Docker in Practice: Volumes and Networking
- 4.6. Process Automation: CI/CD Pipelines
- 4.7. Application Lifecycle: Artifacts and Deployment

UEC: (Prof. Hiroki Takahashi, Prof. Lu JIN)

- 4.8. ...

5. Edge-cloud continuum computing

UEC: (Zhi LIU) First half of the course at PUT (3rd week September)

- 5.1. Session 1: Introduction (U1) - Basic concepts of optimization and an overview of the edge-cloud continuum.
- 5.2. Session 2: Convex Sets and Convex Functions (U2) - Mathematical foundations of optimization: Properties of convex sets and convex functions.
- 5.3. Session 3: Convex Optimization Problems: Basic Concepts and Examples (U3) - Fundamental concepts and formulation of various optimization problems.
- 5.4. Session 4: Convex Optimization Problems: Solutions and Duality (U4) - Solution processes and the theory of dual problems.
- 5.5. Session 5: KKT Conditions and CVX: Introduction and Programming (U5) - Understanding optimality conditions and programming using optimization tools.
- 5.6. Session 6: Approximation, Fitting, and Application Cases (U6) - Approximation methods and common use cases for optimization.
- 5.7. Session 7: Markov Decision Process (MDP) and Its Applications (U7) - Foundations and applications of dynamic decision-making models.

PUT: (Prof. Norbert Langner)

- 5.8. Introduction to configuration management (Ansible, bash recap)
- 5.9. Introduction to Containerization (Docker, Podman)
- 5.10. Container orchestration (Kubernetes)
- 5.11. Public cloud computing basics
- 5.12. Infrastructure as Code (with Terraform)
- 5.13. Application architecture review (monolith, microservices)
- 5.14. Research Challenges in Edge to Cloud Continuum